Declined Options as Reference Points: Evidence from the Field

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#### Sunk costs



Arkes & Blumer, 1985; Shefrin & Statman, 1985; Thaler & Johnson, 1990; Odean, 1998; Genesove & Mayer, 2001



## Declined options



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- 3. Anticipate regretting losses. (Camille et al, 2004; Coricelli et al, 2005)
- 4. Avoid anticipated regret.

(Zeelenberg, 1999)

Labor supply

# UBER 💛 VIG

# Consumption



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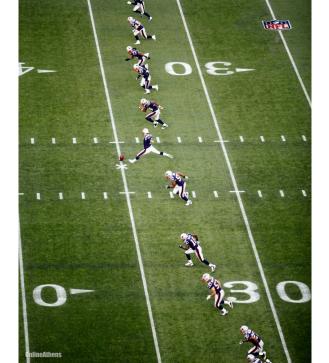
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Solution:

- 1. Natural experiment with quasi-random assignment of option.
- 2. Option is almost always declined.





#### Data

Play-by-play data from NFL kickoffs (2000-10).

- Yard line where kickoff is fielded.
- Touchback decision, if fielded in end zone.
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- Restrict to kickoffs fielded within 2 yards of goal line.
- ▶ 98% of kickoffs fielded from just inside the goal line are returned.

#### Results

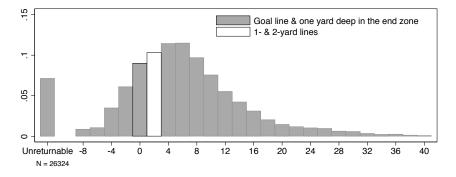
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Consistent with loss aversion around the counterfactual outcome of declined option.

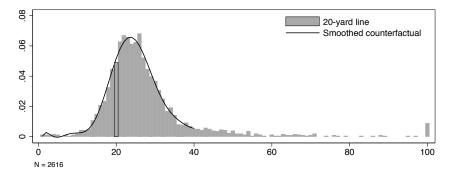
No evidence of manipulation near boundary

#### Distribution of kickoff distance



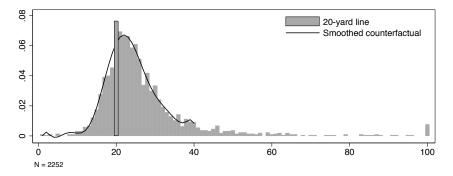
Returns from 1- & 2-yard lines

#### Distribution of return distance



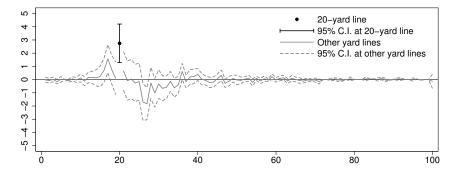
Returns from goal line & 1 yard deep in end zone

Distribution of return distance



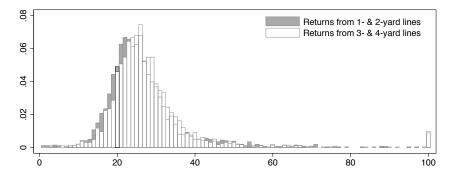
#### Treatment effect

#### Difference in distributions of return distance across goal line



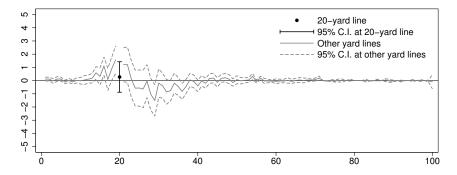
Head start

#### Distributions of return distance



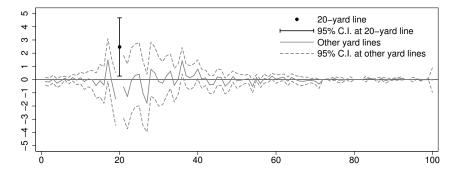
#### Head-start effect

Difference in distributions of return distance across 2-yard line



#### Difference in difference

#### Difference between treatment effect and head-start effect



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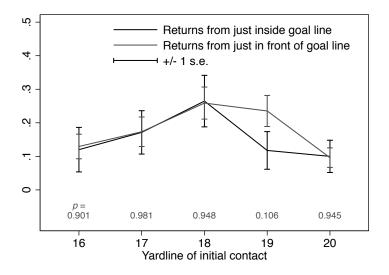
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- 3. Mercy by game officials.

# Appendix

#### Falling forward for a yard

P(tackle at 20|initial contact at y) for returns within 2 yards of goal line



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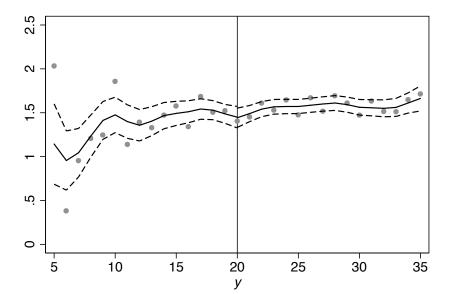
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Find  $\{e_R^*, e_K^*\}$  at each yard line of contact given preferences over y

## Normative preferences

Average number of points scored on drives that start at y.



Reference-independent (RI) value function

$$b_{R}^{RI}(y) = m(y-20)$$

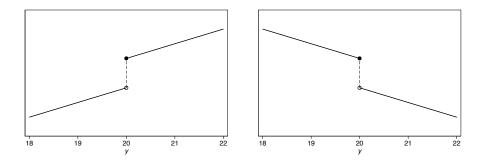
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# Loss-averse (LA) value function

$$b_{R}^{LA}(y) = \begin{cases} m(y-20) & y \ge 20\\ m(y-20) - \Delta & y < 20 \end{cases} \qquad b_{K}^{LA}(y) = \begin{cases} m(20-y) - \Delta & y > 20\\ m(20-y) & y \le 20 \end{cases}$$



Equilibrium effort levels  $\{e_R, e_K\}$ 

Yard line of contact

			19		
RI	RI	$\{L, L\}$	$\{L, L\}$	$\{L, L\}$	$\{L, L\}$
LA	RI	$\{L, L\}$	$ \begin{array}{c} \{L,L\} \\ \{H,L\} \end{array} $	$\{L, L\}$	$\{L, L\}$
RI	LA	$\{L, L\}$	$\{L, L\}$	$\{L, H\}$	$\{L, L\}$

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Yard line of contact

b <sub>R</sub>	b <sub>K</sub>	18	19	20	21
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- 2. If  $R \to LA$  and  $K \to RI$ , P(tackle at y) jumps at 20 from left.
- 3. If  $R \to RI$  and  $K \to LA$ , P(tackle at y) jumps at 20 from right.
- 4. If  $R \to LA$  and  $K \to LA$ , P(tackle at y) spikes at 20.

Loss aversion by R or K?

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$$\delta_{19} + \gamma_R = \delta_{20} - \gamma_R - \gamma_K = \delta_{21} + \gamma_K$$

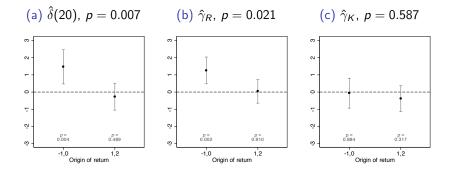
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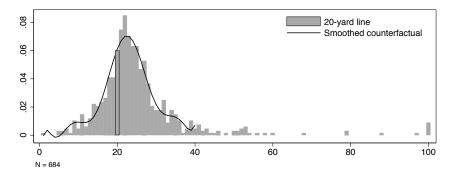
$$\gamma_R = rac{1}{3}(\delta_{21} + \delta_{20} - 2\delta_{19}) \qquad \gamma_K = rac{1}{3}(\delta_{19} + \delta_{20} - 2\delta_{21})$$

#### Mass displacement estimates



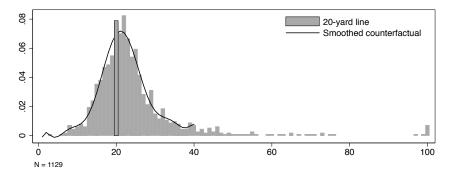
Returns from 1- & 2-yard lines (after)

#### Distribution of return distance



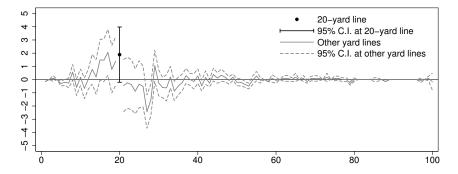
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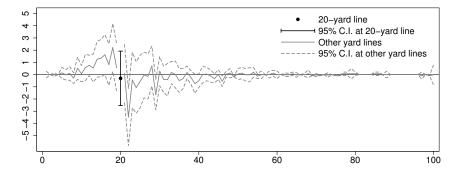
### Treatment effect (after)

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### Head-start effect (after)

#### Difference in distributions of return distance across 2-yard line



Difference in difference (after)

Difference between treatment effect and head-start effect

